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10. (New) The motor according to claim 8, further comprising a correction unit assigned to the control unit that delivers, to the output stages, the control signals determined according to the specified setpoint, either unchanged or as reduced control signals, as a function of the magnitude of the supply voltage.

11. (New) The motor according to claim 10, wherein the control signals are delivered unchanged to the output stages until reaching the nominal voltage, the pulse width being reduced according to a setting provided by the correction unit only when the supply voltage begins to increase.

12. (New) The motor according to claim 10, wherein the correction unit is integrated into the control unit, which delivers the control signals to the output stages, either unchanged or with a reduced pulse width, as a function of the magnitude of the supply voltage.

13. (New) The motor according to claim 8, wherein the reduction of the pulse width of the control signals takes place as a function of a speed of the motor.

This Preliminary Amendment cancels without prejudice original claims 1-7 and substitute claim 1 in the underlying PCT Application No. PCT/DE00/03055, and adds